

10 Karmarkars Algorithm

We want to solve the following linear program:

- ▶ $\min v = c^t x$ subject to $Ax = 0$ and $x \in \Delta$.
- ▶ Here $\Delta = \{x \in \mathbb{R}^n \mid e^t x = 1, x \geq 0\}$ with $e^t = (1, \dots, 1)$ denotes the **standard simplex** in \mathbb{R}^n .

Further assumptions:

- ▶ A is an $m \times n$ matrix with rank m .
- ▶ $Ae = 0$, i.e., the center of the simplex is feasible.
- ▶ The optimum solution is 0.

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Suppose you start with $\max\{c^T x \mid Ax = b; x \geq 0\}$.

• Multiply c by -1 and do a minimization, we minimize $-c^T x$.

• We can check for feasibility by using the two phase

algorithm, we can assume that LP is feasible.

• Complete the dual, pack primal and dual into one LP and minimize the duality gap.

• Add a new variable pair x_i, x_i' (both restricted to be positive) and the constraint $2x_i x_i' = 1$.

• Add $(1 - (\sum x_i x_i'))b_i = -b_i$ to every constraint.

• If A does not have full row rank we can delete constraints (or conclude that the LP is infeasible).

• We'll handle that next.

We still need to make e/n feasible.

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- ▶ Multiply c by -1 and do a minimization. \Rightarrow **minimization problem**
- ▶ We can check for feasibility by using the two phase algorithm. \Rightarrow **can assume that LP is feasible.**
- ▶ Compute the dual; pack primal and dual into one LP and minimize the duality gap. \Rightarrow **optimum is 0**
- ▶ Add a new variable pair x_ℓ, x'_ℓ (both restricted to be positive) and the constraint $\sum_i x_i = 1$. \Rightarrow **solution in simplex**
- ▶ Add $-(\sum_i x_i)b_i = -b_i$ to every constraint. \Rightarrow **vector b is 0**
- ▶ If A does not have full row rank we can delete constraints (or conclude that the LP is infeasible).
 \Rightarrow **A has full row rank**

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The algorithm computes **strictly feasible** interior points $x^{(0)} = \frac{e}{n}, x^{(1)}, x^{(2)}, \dots$ with

$$c^t x^{(k)} \leq 2^{-\Theta(L)} c^t x^{(0)}$$

For $k = \Theta(L)$. A point x is **strictly feasible** if $x > 0$.

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Iteration:

1. Distort the problem by mapping the simplex onto itself so that the **current point** \bar{x} moves to the center.
2. Project the optimization direction c onto the feasible region. Determine a distance to travel along this direction such that you do not leave the simplex (and you do not touch the border). \hat{x}_{new} is the point you reached.
3. Do a backtransformation to transform \hat{x} into your new point \bar{x}_{new} .

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The Transformation

Let $\tilde{Y} = \text{diag}(\tilde{x})$ the diagonal matrix with entries \tilde{x} on the diagonal.

Define

$$F_{\tilde{x}} : x \mapsto \frac{\tilde{Y}^{-1}x}{e^t \tilde{Y}^{-1}x}.$$

The inverse function is

$$F_{\tilde{x}}^{-1} : \hat{x} \mapsto \frac{\tilde{Y}\hat{x}}{e^t \tilde{Y}\hat{x}}.$$

Note that $\tilde{x} > 0$ in every coordinate. Therefore the above is well defined.

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Note that $\bar{x} > 0$ in every coordinate. Therefore the above is well defined.

Properties

$F_{\hat{x}}^{-1}$ really is the inverse of $F_{\hat{x}}$:

$$F_{\hat{x}}(F_{\hat{x}}^{-1}(\hat{x})) = \frac{\bar{Y}^{-1} \frac{\bar{Y}\hat{x}}{e^{t\bar{Y}\hat{x}}}}{e^{t\bar{Y}^{-1} \frac{\bar{Y}\hat{x}}{e^{t\bar{Y}\hat{x}}}}} = \frac{\hat{x}}{e^{t\hat{x}}} = \hat{x}$$

because $\hat{x} \in \Delta$.

Note that in particular every $\hat{x} \in \Delta$ has a preimage (Urbild) under $F_{\hat{x}}$.

Properties

\bar{x} is mapped to e/n

$$F_{\bar{x}}(\bar{x}) = \frac{\bar{Y}^{-1}\bar{x}}{e^t\bar{Y}^{-1}\bar{x}} = \frac{e}{e^te} = \frac{e}{n}$$

A unit vectors e_i is mapped to itself:

$$F_{\tilde{x}}(e_i) = \frac{\tilde{Y}^{-1}e_i}{e^t \tilde{Y}^{-1}e_i} = \frac{(0, \dots, 0, 1/\tilde{x}_i, 0, \dots, 0)^t}{e^t (0, \dots, 0, 1/\tilde{x}_i, 0, \dots, 0)^t} = e_i$$

All nodes of the simplex are mapped to the simplex:

$$F_{\bar{x}}(\mathbf{x}) = \frac{\bar{Y}^{-1}\mathbf{x}}{e^t \bar{Y}^{-1}\mathbf{x}} = \frac{\left(\frac{x_1}{\bar{x}_1}, \dots, \frac{x_n}{\bar{x}_n}\right)^t}{e^t \left(\frac{x_1}{\bar{x}_1}, \dots, \frac{x_n}{\bar{x}_n}\right)^t} = \frac{\left(\frac{x_1}{\bar{x}_1}, \dots, \frac{x_n}{\bar{x}_n}\right)^t}{\sum_i \frac{x_i}{\bar{x}_i}} \in \Delta$$

The Transformation

Easy to check:

- ▶ $F_{\bar{x}}^{-1}$ really is the inverse of $F_{\bar{x}}$.
- ▶ \bar{x} is mapped to e/n .
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Since the optimum solution is 0 this problem is the same as

$$\min\{\hat{c}^t \hat{x} \mid \hat{A} \hat{x} = 0, \hat{x} \in \Delta\}$$

with $\hat{c} = \bar{Y}^t c = \bar{Y} c$ and $\hat{A} = A \bar{Y}$.

We still need to make e/n feasible.

- ▶ We know that our LP is feasible. Let \bar{x} be a feasible point.
- ▶ Apply $F_{\bar{x}}$, and solve

$$\min\{\hat{c}^t x \mid \hat{A}x = 0; x \in \Delta\}$$

- ▶ The feasible point is moved to the center.

10 Karmarkars Algorithm

When computing \hat{x}_{new} we do not want to leave the simplex or touch its boundary (why?).

For this we compute the radius of a ball that completely lies in the simplex.

$$B\left(\frac{e}{n}, \rho\right) = \left\{x \in \mathbb{R}^n \mid \left\|x - \frac{e}{n}\right\| \leq \rho\right\}.$$

We are looking for the largest radius r such that

$$B\left(\frac{e}{n}, r\right) \cap \{x \mid e^t x = 1\} \subseteq \Delta.$$

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This holds for $r = \left\| \frac{e}{n} - (e - e_1) \frac{1}{n-1} \right\|$. (r is the distance between the center e/n and the center of the $(n-1)$ -dimensional simplex obtained by intersecting a side ($x_i = 0$) of the unit cube with Δ .)

This gives $r = \frac{1}{\sqrt{n(n-1)}}$.

Now we consider the problem

$$\min\{\hat{c}^t x \mid \hat{A}x = 0, x \in B(e/n, r) \cap \Delta\}$$

This problem is easy to solve!!!

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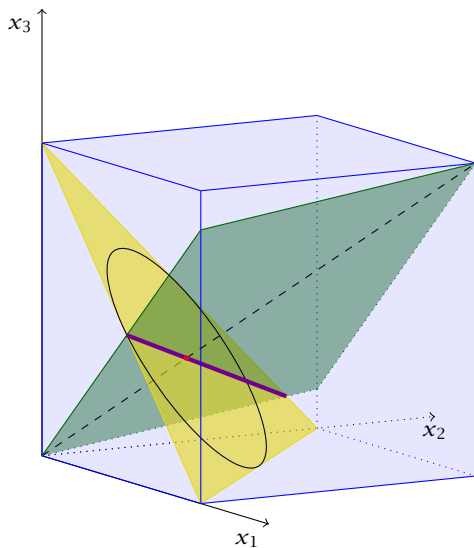
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The Simplex



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Ideally we would like to go in direction of $-\hat{c}$ (starting from the center of the simplex).

However, doing this may violate constraints $\hat{A}\hat{x} = 0$ or the constraint $\hat{x} \in \Delta$.

Therefore we first project \hat{c} on the nullspace of

$$B = \begin{pmatrix} \hat{A} \\ e^t \end{pmatrix}$$

We use

$$P = I - B^t (BB^t)^{-1} B$$

Then

$$\hat{d} = P\hat{c}$$

is the required projection.

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We get the new point

$$\hat{x}(\rho) = \frac{e}{n} - \rho \frac{\hat{d}}{\|\hat{d}\|}$$

for $\rho < r$.

Choose $\rho = \alpha r$ with $\alpha = 1/4$.

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Iteration of Karmarkars Algorithm

- ▶ Current solution \bar{x} . $\bar{Y} := \text{diag}(\bar{x}_1, \dots, \bar{x}_n)$.
- ▶ Transform problem via $F_{\bar{x}}(x) = \frac{\bar{Y}^{-1}x}{e^t \bar{Y}^{-1}x}$.
Let $\hat{c} = \bar{Y}c$, and $\hat{A} = A\bar{Y}$.

- ▶ Compute

$$\hat{d} = (I - B^t(BB^t)^{-1}B)\hat{c} ,$$

where $B = \begin{pmatrix} \hat{A} \\ e^t \end{pmatrix}$.

- ▶ Set

$$\hat{x}_{\text{new}} = \frac{e}{n} - \rho \frac{\hat{d}}{\|\hat{d}\|} ,$$

with $\rho = \alpha r$ with $\alpha = 1/4$ and $r = 1/\sqrt{n(n-1)}$.

- ▶ Compute $\bar{x}_{\text{new}} = F_{\bar{x}}^{-1}(\hat{x}_{\text{new}})$.

Lemma 2

The new point \hat{x}_{new} in the transformed space is the point that minimizes the cost $\hat{c}^t \hat{x}$ among all feasible points in $B(\frac{\epsilon}{n}, \rho)$.

Proof: Let \hat{z} be another feasible point in $B(\frac{\epsilon}{n}, \rho)$.

Proof: Let \hat{z} be another feasible point in $B(\frac{\rho}{n}, \rho)$.

As $\hat{A}\hat{z} = 0$, $\hat{A}\hat{x}_{\text{new}} = 0$, $e^t \hat{z} = 1$, $e^t \hat{x}_{\text{new}} = 1$

Proof: Let \hat{z} be another feasible point in $B(\frac{\epsilon}{n}, \rho)$.

As $\hat{A}\hat{z} = 0$, $\hat{A}\hat{x}_{\text{new}} = 0$, $e^t \hat{z} = 1$, $e^t \hat{x}_{\text{new}} = 1$ we have

$$B(\hat{x}_{\text{new}} - \hat{z}) = 0 .$$

Proof: Let \hat{z} be another feasible point in $B(\frac{\rho}{n}, \rho)$.

As $\hat{A}\hat{z} = 0$, $\hat{A}\hat{x}_{\text{new}} = 0$, $e^t \hat{z} = 1$, $e^t \hat{x}_{\text{new}} = 1$ we have

$$B(\hat{x}_{\text{new}} - \hat{z}) = 0 .$$

Further,

$$(\hat{c} - \hat{d})^t$$

Proof: Let \hat{z} be another feasible point in $B(\frac{\rho}{n}, \rho)$.

As $\hat{A}\hat{z} = 0$, $\hat{A}\hat{x}_{\text{new}} = 0$, $e^t \hat{z} = 1$, $e^t \hat{x}_{\text{new}} = 1$ we have

$$B(\hat{x}_{\text{new}} - \hat{z}) = 0 .$$

Further,

$$(\hat{c} - \hat{d})^t = (\hat{c} - P\hat{c})^t$$

Proof: Let \hat{z} be another feasible point in $B(\frac{\epsilon}{n}, \rho)$.

As $\hat{A}\hat{z} = 0$, $\hat{A}\hat{x}_{\text{new}} = 0$, $e^t \hat{z} = 1$, $e^t \hat{x}_{\text{new}} = 1$ we have

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Further,

$$\begin{aligned}(\hat{c} - \hat{d})^t &= (\hat{c} - P\hat{c})^t \\ &= (B^t(BB^t)^{-1}B\hat{c})^t\end{aligned}$$

Proof: Let \hat{z} be another feasible point in $B(\frac{\epsilon}{n}, \rho)$.

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Hence, we get

$$(\hat{c} - \hat{d})^t (\hat{x}_{\text{new}} - \hat{z}) = 0$$

Proof: Let \hat{z} be another feasible point in $B(\frac{\epsilon}{n}, \rho)$.

As $\hat{A}\hat{z} = 0$, $\hat{A}\hat{x}_{\text{new}} = 0$, $e^t \hat{z} = 1$, $e^t \hat{x}_{\text{new}} = 1$ we have

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Hence, we get

$$(\hat{c} - \hat{d})^t(\hat{x}_{\text{new}} - \hat{z}) = 0 \text{ or } \hat{c}^t(\hat{x}_{\text{new}} - \hat{z}) = \hat{d}^t(\hat{x}_{\text{new}} - \hat{z})$$

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which means that the cost-difference between \hat{x}_{new} and \hat{z} is the same measured w.r.t. the cost-vector \hat{c} or the projected cost-vector \hat{d} .

But

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as $\frac{e}{n} - \hat{z}$ is a vector of length at most ρ .

This gives $\hat{d}(\hat{x}_{\text{new}} - \hat{z}) \leq 0$ and therefore $\hat{c}\hat{x}_{\text{new}} \leq \hat{c}\hat{z}$.

In order to measure the progress of the algorithm we introduce a **potential function** f :

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- ▶ The function f is invariant to scaling (i.e., $f(k\mathbf{x}) = f(\mathbf{x})$).
- ▶ The potential function essentially measures **cost** (note the term $n \ln(c^t \mathbf{x})$) but it penalizes us for choosing x_j values very small (by the term $-\sum_j \ln(x_j)$; note that $-\ln(x_j)$ is always positive).

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Observation:

This means the potential of a point in the transformed space is simply the potential of its pre-image under F .

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Observation:

This means the potential of a point in the transformed space is simply the potential of its pre-image under F .

Note that if we are interested in **potential-change** we can ignore the additive term above. Then f and \hat{f} have the same form; only c is replaced by \hat{c} .

The basic idea is to show that one iteration of Karmarkar results in a constant decrease of \hat{f} . This means

$$\hat{f}(\hat{x}_{\text{new}}) \leq \hat{f}\left(\frac{e}{n}\right) - \delta ,$$

where δ is a constant.

The basic idea is to show that one iteration of Karmarkar results in a constant decrease of \hat{f} . This means

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where δ is a constant.

This gives

$$f(\tilde{x}_{\text{new}}) \leq f(\tilde{x}) - \delta .$$

Lemma 3

There is a feasible point z (i.e., $\hat{A}z = 0$) in $B(\frac{e}{n}, \rho) \cap \Delta$ that has

$$\hat{f}(z) \leq \hat{f}\left(\frac{e}{n}\right) - \delta$$

with $\delta = \ln(1 + \alpha)$.

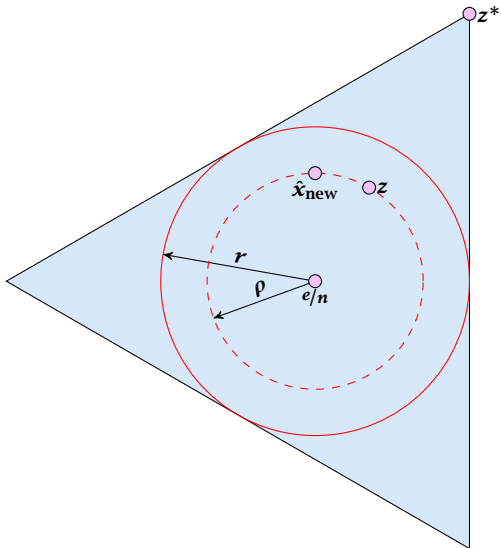
Lemma 3

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with $\delta = \ln(1 + \alpha)$.

Note that this shows the existence of a good point within the ball. In general it will be difficult to find this point.



Let z^* be the feasible point in the transformed space where $\hat{c}^t x$ is minimized. (Note that in contrast \hat{x}_{new} is the point in the **intersection of the feasible region and $B(\frac{e}{n}, \rho)$** that minimizes this function; in general $z^* \neq \hat{x}_{\text{new}}$)

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z^* must lie at the boundary of the simplex. This means $z^* \notin B(\frac{e}{n}, \rho)$.

The point z we want to use lies farthest in the direction from $\frac{e}{n}$ to z^* , namely

$$z = (1 - \lambda) \frac{e}{n} + \lambda z^*$$

for some positive $\lambda < 1$.

Hence,

$$\hat{c}^t z = (1 - \lambda) \hat{c}^t \frac{e}{n} + \lambda \hat{c}^t z^*$$

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Therefore,

$$\frac{\hat{c}^t \frac{e}{n}}{\hat{c}^t z} = \frac{1}{1 - \lambda}$$

The improvement in the potential function is

$$\hat{f}\left(\frac{e}{n}\right) - \hat{f}(z)$$

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We can use the fact that for non-negative s_i

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αr

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Then

$$1 + n \frac{\lambda}{1-\lambda} \geq 1 + \frac{n\alpha}{n-\alpha-1} \geq 1 + \alpha$$

This gives the lemma.

Lemma 4

If we choose $\alpha = 1/4$ and $n \geq 4$ in Karmarkars algorithm the point \hat{x}_{new} satisfies

$$\hat{f}(\hat{x}_{\text{new}}) \leq \hat{f}\left(\frac{e}{n}\right) - \delta$$

with $\delta = 1/10$.

Proof:

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$$g(\hat{x}) =$$

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$$g(\hat{x}) = n \ln \frac{\hat{c}^t \hat{x}}{\hat{c}^t \frac{e}{n}}$$

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$$\begin{aligned}g(\hat{x}) &= n \ln \frac{\hat{c}^t \hat{x}}{\hat{c}^t \frac{e}{n}} \\ &= n(\ln \hat{c}^t \hat{x} - \ln \hat{c}^t \frac{e}{n}) .\end{aligned}$$

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$$\begin{aligned}g(\hat{x}) &= n \ln \frac{\hat{c}^t \hat{x}}{\hat{c}^t \frac{e}{n}} \\ &= n(\ln \hat{c}^t \hat{x} - \ln \hat{c}^t \frac{e}{n}) .\end{aligned}$$

This is the change in the **cost part** of the potential function when going from the center $\frac{e}{n}$ to the point \hat{x} in the **transformed space**.

Similar, the **penalty** when going from $\frac{e}{n}$ to w increases by

$$h(\hat{x}) = \text{pen}(\hat{x}) - \text{pen}\left(\frac{e}{n}\right) = - \sum_j \ln \frac{\hat{x}_j}{\frac{1}{n}}$$

where $\text{pen}(v) = - \sum_j \ln(v_j)$.

We want to derive a lower bound on

$$\hat{f}\left(\frac{e}{n}\right) - \hat{f}(\hat{x}_{\text{new}})$$

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$$\begin{aligned}\hat{f}\left(\frac{e}{n}\right) - \hat{f}(\hat{x}_{\text{new}}) &= [\hat{f}\left(\frac{e}{n}\right) - \hat{f}(z)] \\ &\quad + h(z) \\ &\quad - h(\hat{x}_{\text{new}}) \\ &\quad + [g(z) - g(\hat{x}_{\text{new}})]\end{aligned}$$

where z is the point in the ball where \hat{f} achieves its minimum.

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We have

$$[\hat{f}(\frac{e}{n}) - \hat{f}(z)] \geq \ln(1 + \alpha)$$

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$$[g(z) - g(\hat{x}_{\text{new}})] \geq 0$$

since \hat{x}_{new} is the point with minimum cost in the ball, and g is monotonically increasing with cost.

We show that the change $h(w)$ in **penalty** when going from e/n to w fulfills

$$|h(w)| \leq \frac{\beta^2}{2(1-\beta)}$$

where $\beta = n\alpha r$ and w is some point in the ball $B(\frac{e}{n}, \alpha r)$.

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Hence,

$$\hat{f}\left(\frac{e}{n}\right) - \hat{f}(\hat{x}_{\text{new}}) \geq \ln(1 + \alpha) - \frac{\beta^2}{(1 - \beta)} .$$

Lemma 5

For $|x| \leq \beta < 1$

$$|\ln(1+x) - x| \leq \frac{x^2}{2(1-\beta)} .$$

This gives for $w \in B(\frac{\epsilon}{n}, \rho)$

$$|h(w)|$$

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$$\begin{aligned} |h(w)| &= \left| \sum_j \ln \frac{w_j}{1/n} \right| \\ &= \left| \sum_j \ln \left(\frac{1/n + (w_j - 1/n)}{1/n} \right) - \sum_j n \left(w_j - \frac{1}{n} \right) \right| \end{aligned}$$

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The decrease in potential is therefore at least

$$\ln(1 + \alpha) - \frac{\beta^2}{1 - \beta}$$

with $\beta = n\alpha r = \alpha\sqrt{\frac{n}{n-1}}$.

It can be shown that this is at least $\frac{1}{10}$ for $n \geq 4$ and $\alpha = 1/4$.

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Let $\tilde{x}^{(k)}$ be the current point after the k -th iteration, and let $\tilde{x}^{(0)} = \frac{e}{n}$.

Then $f(\tilde{x}^{(k)}) \leq f(e/n) - k/10$.

This gives

$$\ln \frac{f(\tilde{x}^{(k)})}{f(e/n)} \leq -k/10 \Rightarrow \ln \frac{c^t \tilde{x}^{(k)}}{c^t \frac{e}{n}} \leq -k/10$$

Choosing $k = 10n(\ell + \ln n)$ with $\ell = \Theta(L)$ we get

$$\frac{c^t \tilde{x}^{(k)}}{c^t \frac{e}{n}} \leq e^{-\ell} \leq 2^{-\ell} .$$

Hence, $\Theta(nL)$ iterations are sufficient. One iteration can be performed in time $\mathcal{O}(n^3)$.

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